

GAITWISE, an automated detection system for lameness in dairy cattle



Annelies Van Nuffel

Stephanie Van Weyenberg

Bart Sonck

Bart De Ketelaere

Tim Van De Gucht

Koen Mertens

Jürgen Vangeyte

Wouter Saeys

Dairy lameness situation

Negative effect on cow health, welfare, longevity and production
High prevalence hugely underestimated

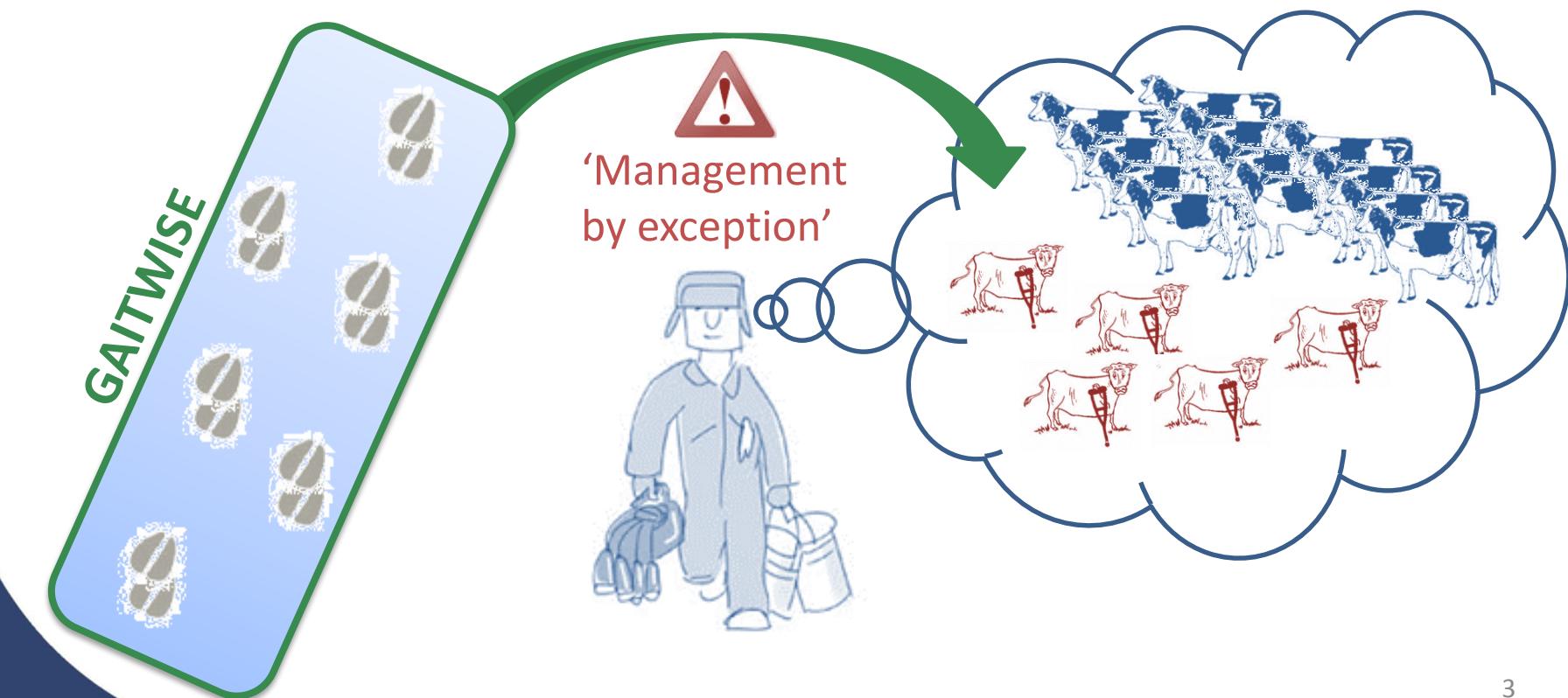
→ Detect those cows that need extra attention



Dairy lameness situation

Negative effect on cow health, welfare, longevity and production
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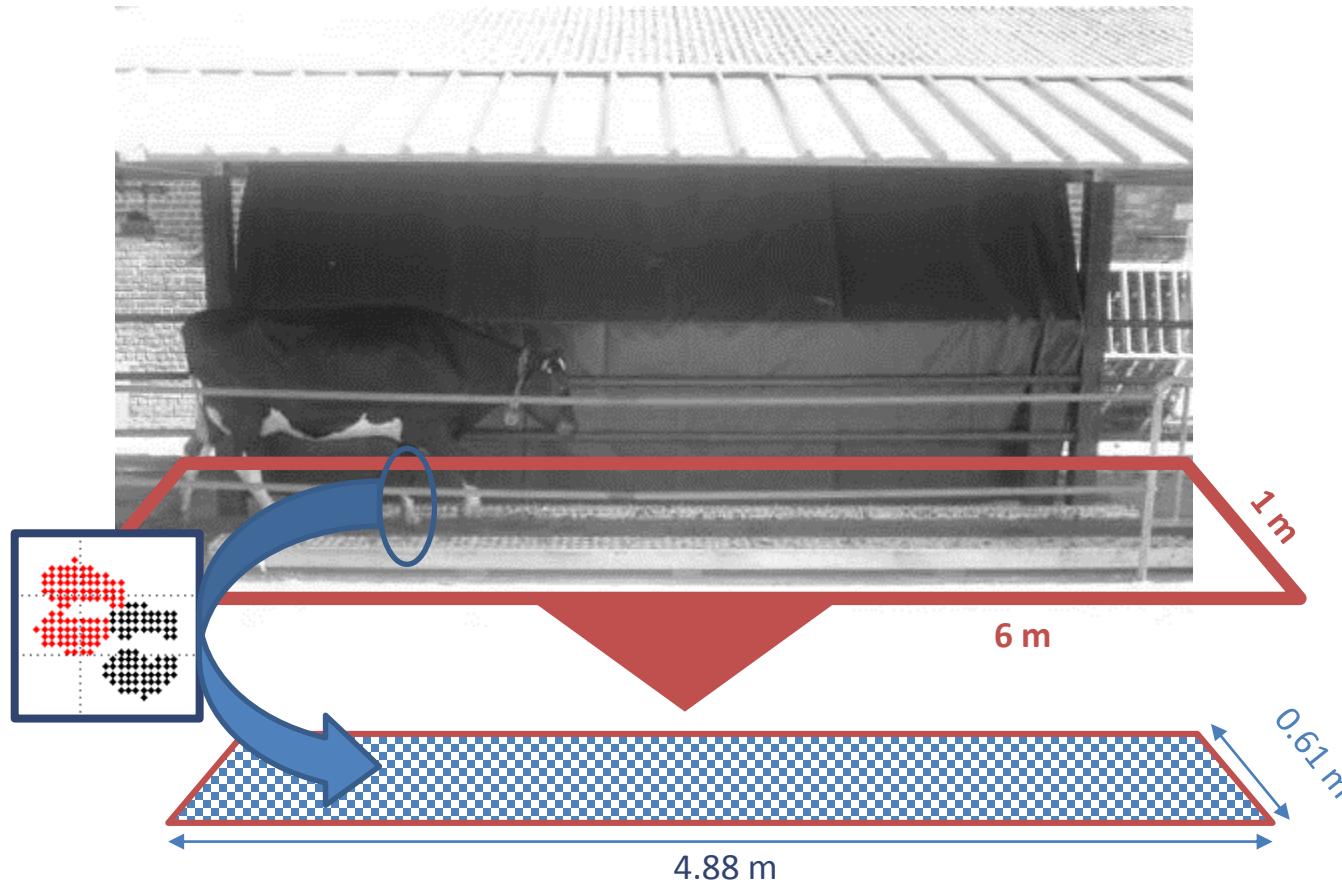
→ Detect those cows that need extra attention



Lameness detection

1. Monitoring cow gait
2. Detection algorithm
to alert for changes
in gait relevant for
lameness

Monitoring cow gait

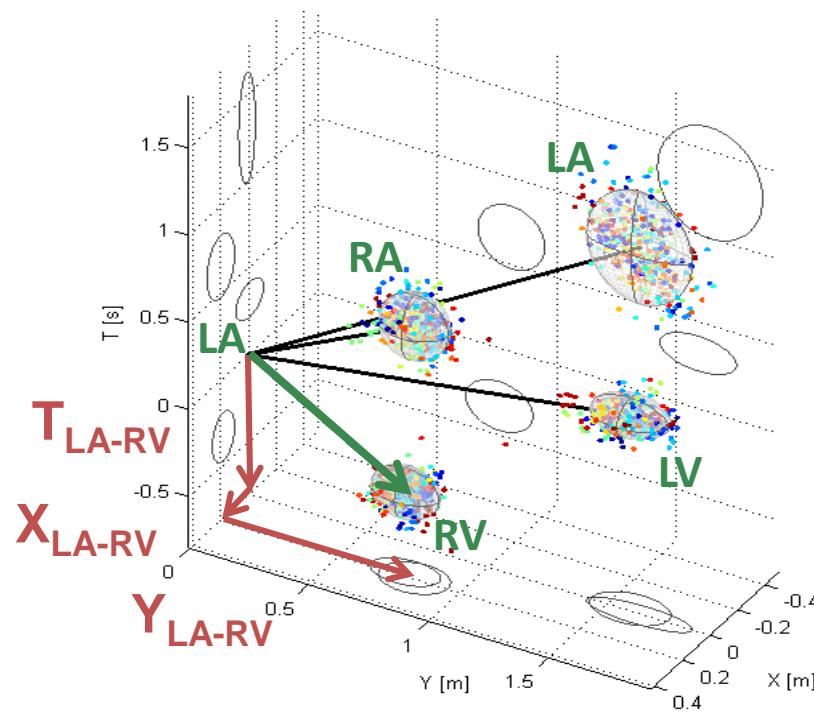


TIME – LOCATION – FORCE

Monitoring cow gait

20 Basic variables

→ Between-imprint gait variables (12)



T_{LA-LA}	X_{LA-LA}	Y_{LA-LA}
T_{LA-RA}	X_{LA-RA}	Y_{LA-RA}
T_{LA-LV}	X_{LA-LV}	Y_{LA-LV}
T_{LA-RV}	X_{LA-RV}	Y_{LA-RV}

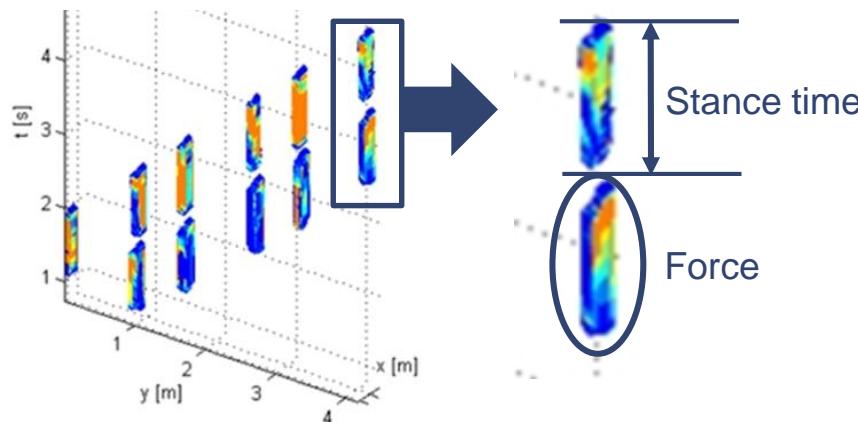
Monitoring cow gait

20 Basic variables

→ Between-imprint gait variables (12)

T_{LA-LA}	X_{LA-LA}	Y_{LA-LA}
T_{LA-RA}	X_{LA-RA}	Y_{LA-RA}
T_{LA-LV}	X_{LA-LV}	Y_{LA-LV}
T_{LA-RV}	X_{LA-RV}	Y_{LA-RV}

→ Within-imprint gait variables (8)



Force _{LA}
Force _{RA}
Force _{LV}
Force _{RV}

Stance time _{LA}
Stance time _{RA}
Stance time _{LV}
Stance time _{RV}

Monitoring cow gait

10 Specific variables

- Stride length
- Stride time
- Stance time
- Step Overlap
- Abduction
- Asymmetry in
 - Stepwidth
 - Steplength
 - Steptime
 - Stancetime
 - Force

Detection algorithm

Gait differences between groups of

Specific variable	Non-lame (39 cow; n=661)	Mildly lame (36 cow; n=126)	Severely lame (42 cow; n=393)	P-value
Stridelength		Slower Shorter strides		
Stridetime				
Stance time				
Step Overlap		Less step overlap		
Abduction		More abduction		
Asym. Stepwidth				
Asym. Steplength				
Asym. Steptime			More asymmetry	
Asym. Stance time				
Asym. Force				

Detection algorithm

Stridelength
~~Stride time~~
Stance time
Step Overlap
Abduction

~~Asymmetry in Stepwidth~~
Asymmetry in Steplength
Asymmetry in Steptime
Asymmetry in Stancetime
~~Asymmetry in Force~~

Cross validation

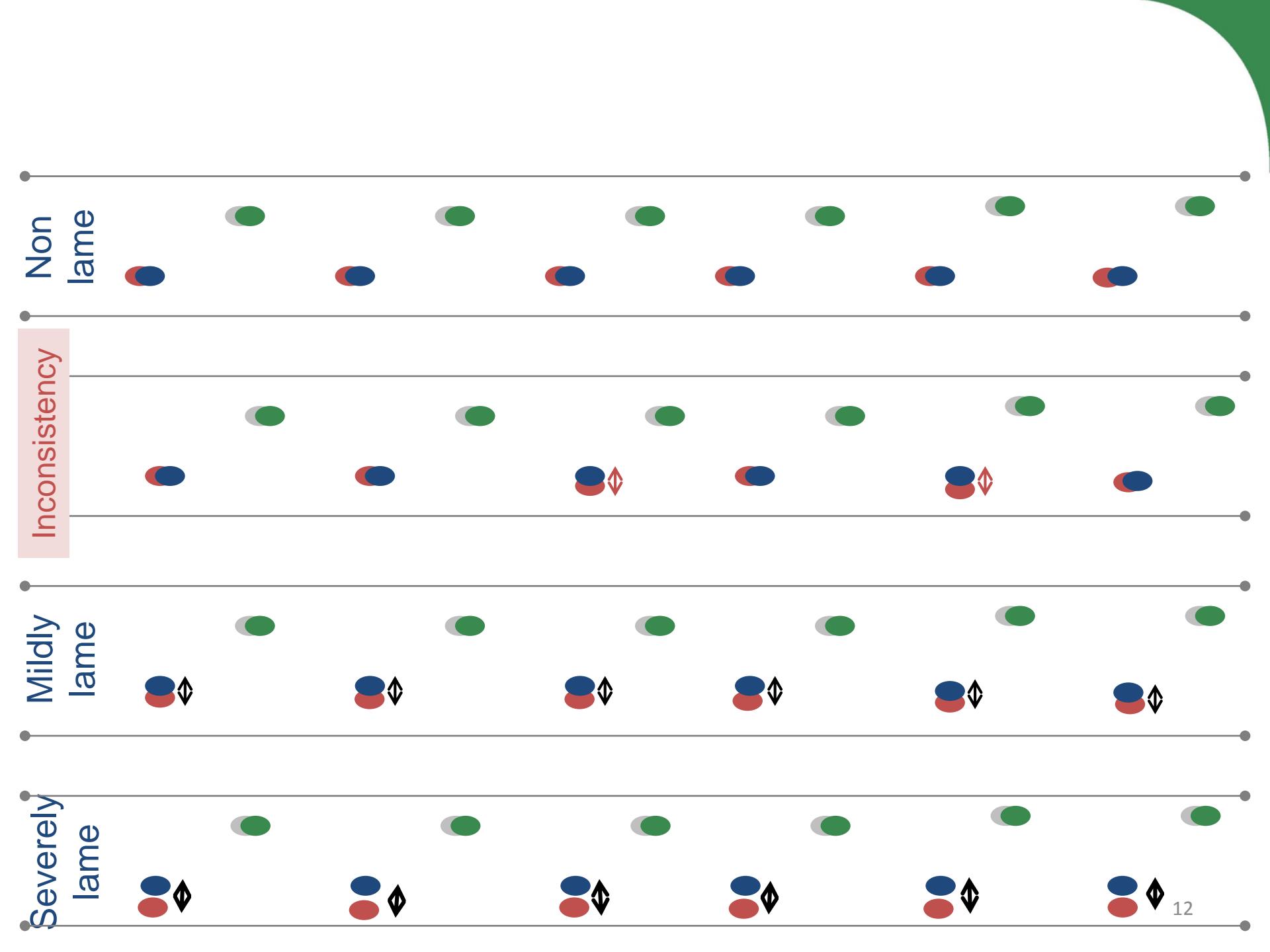
82 %

		Model			Sensitivity
Reference		NON-lame	MILDLY lame	SEVERELY lame	
Specificity	NON-lame				81
	MILDLY lame				76
	SEVERELY lame				88

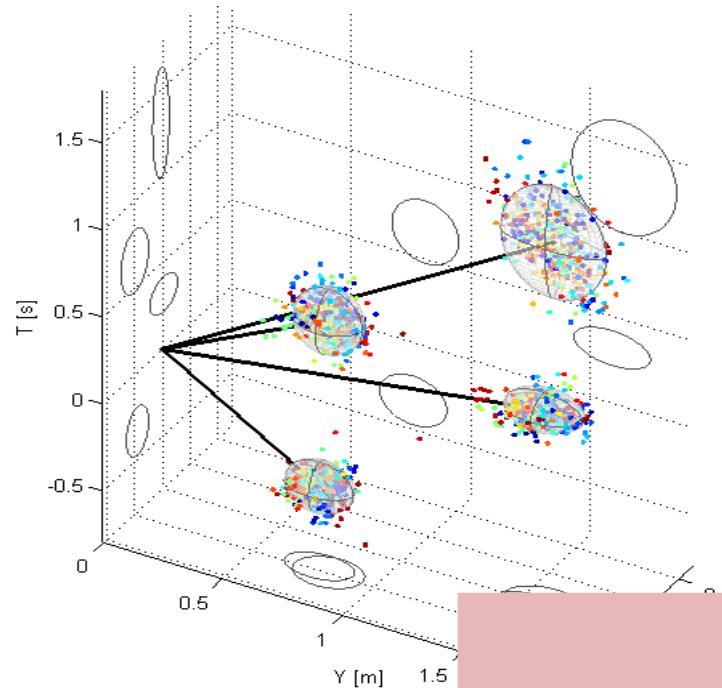
Detection algorithm

How to improve the misclassification of mildly lame cows?

- *Other 'normal' causes of changes in gait variables*
→ presentation 5.4 in session 5
- *Look for other variables more suited for detection of mildly lame cows*
→ *Variables of gait inconsistency*



Variables of gait inconsistency



INCONSISTENCY ...

T LA-LA	X LA-LA	Y LA-LA
T LA-RA	X LA-RA	Y LA-RA
T LA-LV	X LA-LV	Y LA-LV
T LA-RV	X LA-RV	Y LA-RV
Stance time LA	Force LA	
Stance time RA	Force RA	
Stance time LV	Force LV	
Stance time RV	Force RV	
T LA-LA	X LA-LA	Y LA-LA
T LA-RA	X LA-RA	Y LA-RA
T LA-LV	X LA-LV	Y LA-LV
T LA-RV	X LA-RV	Y LA-RV
Stance time LA	Force LA	
Stance time RA	Force RA	
Stance time LV	Force LV	
Stance time RV	Force RV	

Detection algorithm

- compare variables between groups of non-lame – mildly lame – severely lame cows

Inconsistency in stepwidth

Inconsistency in steplength ✓

Inconsistency in steptime ✓

Inconsistency in stance time✓

Inconsistency in force

- Two case-control studies (Van Nuffel et al. 2013)

Detection algorithm

Classification-model

20 Basic variables

+ 20 Inconsistency variables

Cross validation

77.4 %

		Model			Sensitivity
Reference		NON-lame	MILDLY lame	SEVERELY lame	
					71
NON-lame					88
MILDLY lame					76
SEVERELY lame					78
Specificity		94	87	86	

Conclusions

&

Suggestions for further development and research

STRENGTHS Gaitwise

- Real-time, automated measurements
- Wide range of variables – relevant for lameness
- Validated detection model

Specific variables

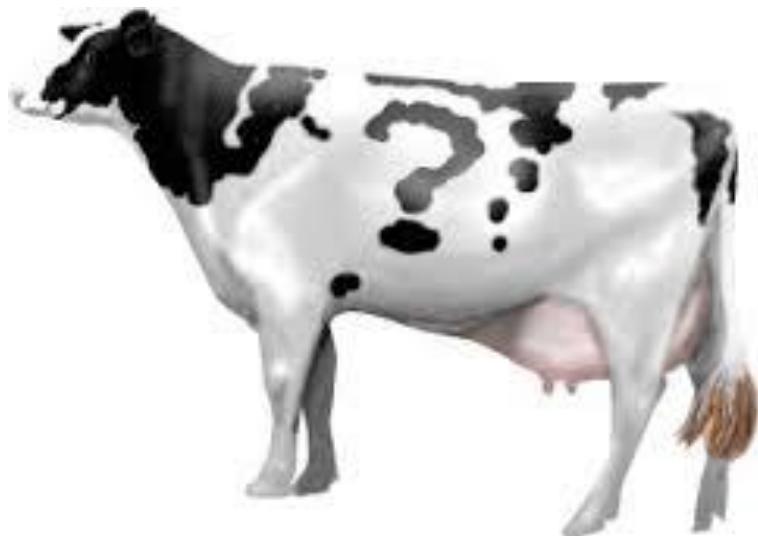
Severely lame → Se 88%
Sp 100%

Inconsistency variables

Mildly lame → Se 88%
Sp 87%

Challenges for further development of Gaitwise

- Reducing cost (downscaling)
 - Improve detection of mildly lame cows
 - Testing new or adjusted gait variables
 - Combining Gaitwise data with other data
 - Improve the detection by using individual thresholds
- SILF-project (poster 9.5.23)



Any questions?

Annelies Van Nuffel

Annelies.vannuffel@ilvo.vlaanderen.be